Towards Smart Cities at the Mental Level via Tentacular AI (TAI) Agents

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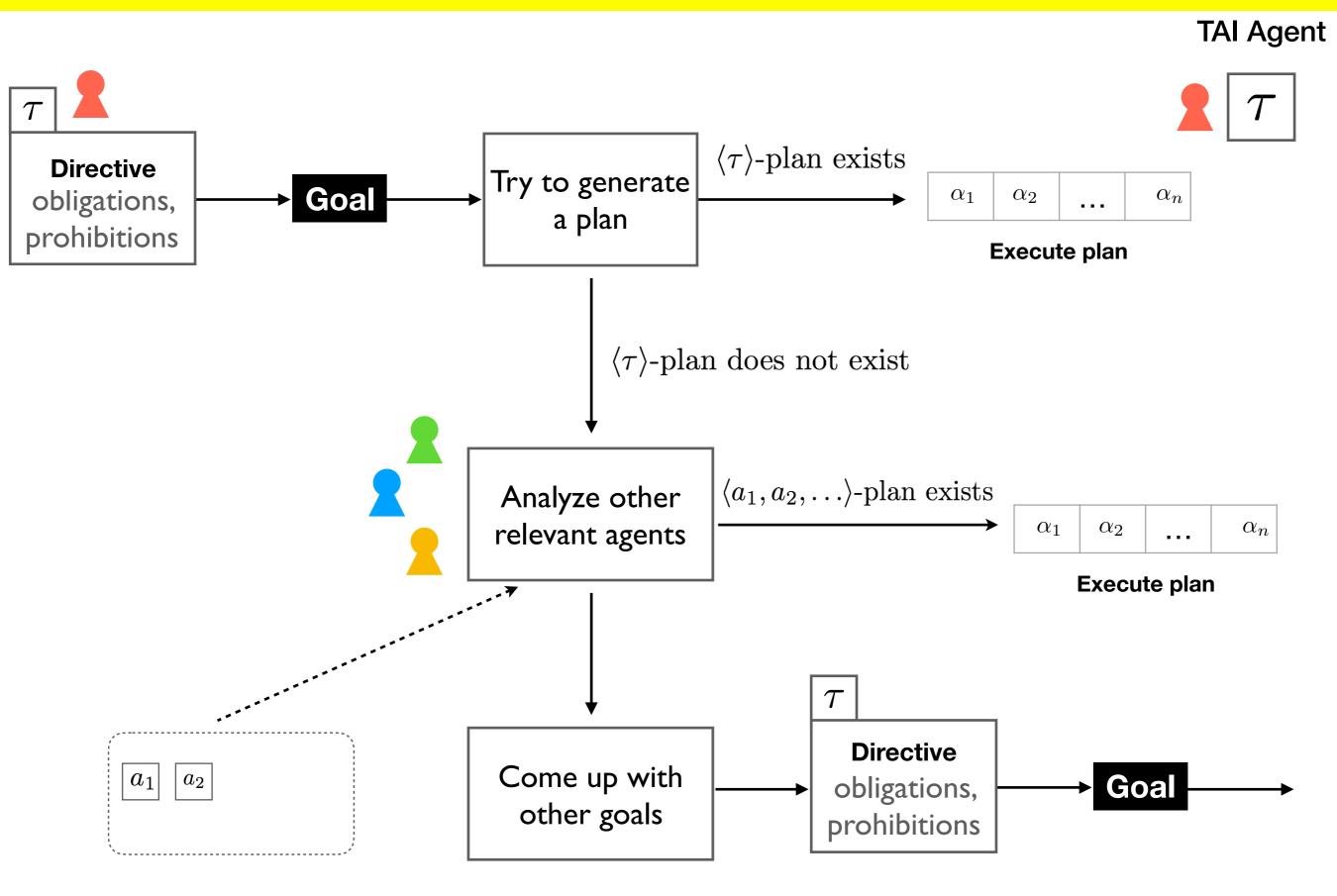


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INFORMAL OVERVIEW



A TAI agent must be ...

- I. capable of **problem-solving** via planning, reasoning, learning, communicating;
- 2. capable of solving at least important instances of problems that are at and/or "above" **Turing-unsolvable problems**;
- 3. able to supply justification, **explanation**, and certification of supplied solutions, how they are arrived at, and that these solutions are safe/ethical;
- 4. capable of **theory-of-mind-level** reasoning, planning, learning, and communicating;
- 5. capable of **creativity**, minimally to the level of so-called "MacGyveresque", or *m*-creativity; and
- 6. in possession of "**tentacular**" power wielded throughout **I/IoT**, edge computing, cyberspace, etc.

Formal Background

- Deontic Cognitive Event Calculus DCEC
 - First Order Multi-Operator Modal Logic
 - Well-Defined Syntax & Inference Schemata
 - Based on Natural Deduction

Sort	Description
Agent	Human and non-human actors.
Time	The Time type stands for time in the domain. E.g. simple, such as t_i , or complex, such as $birthday(son(jack))$.
Event	Used for events in the domain.
ActionType	Action types are abstract actions. They are in- stantiated at particular times by actors. Exam- ple: eating.
Action	A subtype of Event for events that occur as actions by agents.
Fluent	Used for representing states of the world in the event calculus.

FORMAL BACKGROUND

Syntax

$$\begin{split} S &::= \text{Agent} \mid \text{ActionType} \mid \text{Action} \sqsubseteq \text{Event} \mid \text{Moment} \mid \text{Fluent} \\ action : \text{Agent} \times \text{ActionType} \rightarrow \text{Action} \\ initially : \text{Fluent} \rightarrow \text{Formula} \\ holds : \text{Fluent} \times \text{Moment} \rightarrow \text{Formula} \\ happens : \text{Event} \times \text{Moment} \rightarrow \text{Formula} \\ clipped : \text{Moment} \times \text{Fluent} \times \text{Moment} \rightarrow \text{Formula} \\ initiates : \text{Event} \times \text{Fluent} \times \text{Moment} \rightarrow \text{Formula} \\ terminates : \text{Event} \times \text{Fluent} \times \text{Moment} \rightarrow \text{Formula} \\ prior : \text{Moment} \times \text{Moment} \rightarrow \text{Formula} \\ t ::= x : S \mid c : S \mid f(t_1, \dots, t_n) \\ \\ \phi ::= \begin{cases} q : \text{Formula} \mid \neg \phi \mid \phi \land \psi \mid \phi \lor \psi \mid \forall x : \phi(x) \mid \\ \mathbf{P}(a, t, \phi) \mid \mathbf{K}(a, t, \phi) \mid \\ \mathbf{O}(a, t, \phi) \mid \mathbf{I}(a, t, \phi) \\ \mathbf{O}(a, t, \phi, (\neg) happens(action(a^*, \alpha), t')) \end{cases} \end{split}$$

Inference Schemata (Fragment)

$$\frac{\mathbf{K}(a, t_{1}, \Gamma), \ \Gamma \vdash \phi, \ t_{1} \leq t_{2}}{\mathbf{K}(a, t_{2}, \phi)} [I_{\mathbf{K}}]$$

$$\frac{\mathbf{B}(a, t_{1}, \Gamma), \ \Gamma \vdash \phi, \ t_{1} \leq t_{2}}{\mathbf{B}(a, t_{2}, \phi)} [I_{\mathbf{B}}]$$

$$\frac{\mathbf{K}(a, t, \phi)}{\phi} [I_{4}] \qquad \frac{t < t', \ \mathbf{I}(a, t, \psi)}{\mathbf{P}(a, t', \psi)} [I_{13}]$$

$$\frac{\mathbf{B}(a, t, \phi) \ \mathbf{B}(a, t, \mathbf{O}(a, t, \phi, \chi)) \ \mathbf{O}(a, t, \phi, \chi)}{\mathbf{K}(a, t, \mathbf{I}(a, t, \chi))} [I_{14}]$$

Differences from Prior Work

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• Expressivity

:goal (Believes! d (hide m plain))}

1. Can handle states of minds of other agents as goals.

2. Quantifiers enable succinct representation of large (infinite) domains.

- Absence/scarcity of standardized domain knowledge.
 - Today's ML can't solve anomalous problems.

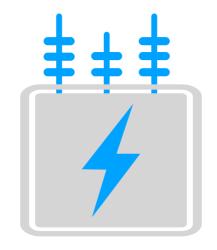
	"The Purloined Letter" "Dupin's reasoning as he goes through the case"
assumptions:	<pre>{1 (Believes! g (hide m elaborate)) 2 (Believes! d (or (hide m elaborate) (hide m plain))) 3 (Believes! m (Believes! g (hide m elaborate))) 4 (if (Believes! m (Believes! g (hide m elaborate))) (hide m plain)) 5 (if (Believes! m (Believes! g (hide m plain))) (hide m elaborate)) 6 (Believes! m (Believes! g (hide m elaborate))) 7 (Believes! d (if (Believes! m (Believes! g (hide m elaborate))) 8 (Believes! d (if (Believes! m (Believes! g (hide m plain))) (hide m elaborate))) 9 (Believes! d (Believes! m (Believes! g (hide m elaborate))))}</pre>

These model an infinite domain

 $\forall x \exists y \mathbf{R} (x, y) \land$ $\forall x, y \neg (\mathbf{R} (x, y) \land \mathbf{R} (y, x)) \land$ $\forall x, y, z (\mathbf{R} (x, y) \land \mathbf{R} (y, z)) \rightarrow \mathbf{R} (x, z)$

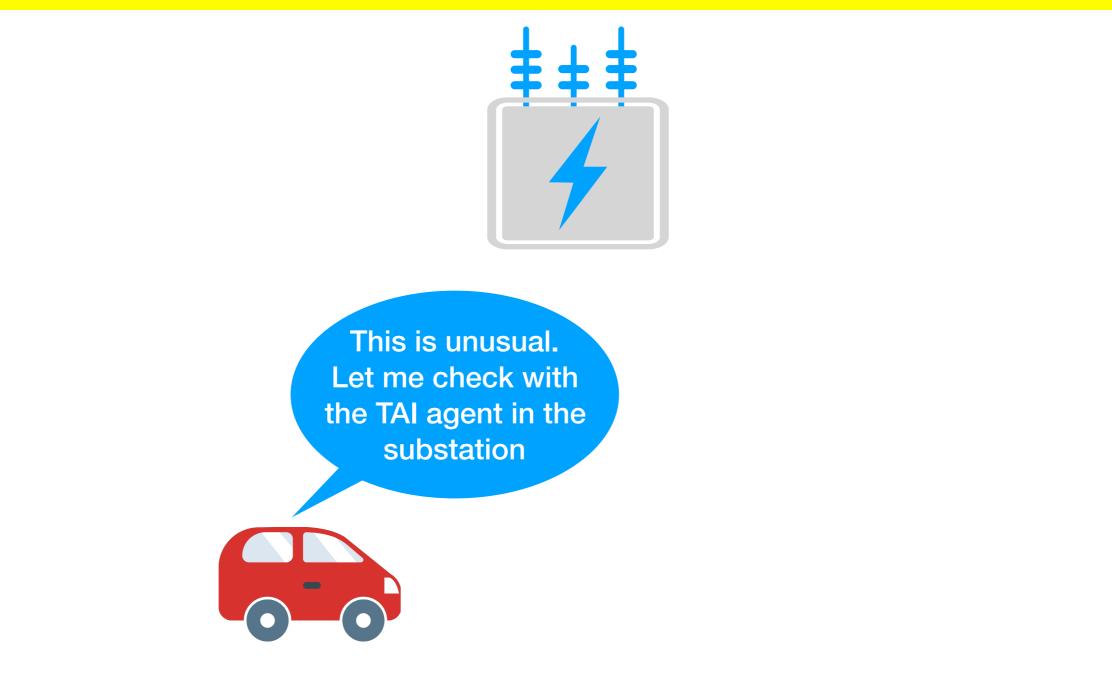
Applications to Smart Cities

Scenario I: Power Outage



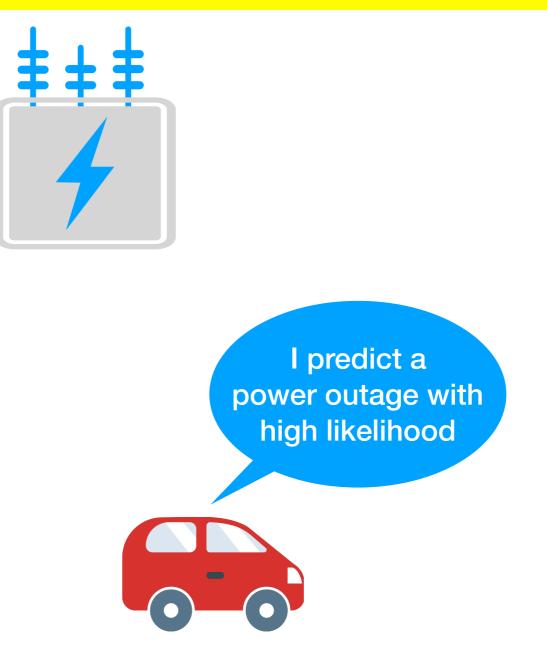
I hear loud noises coming from the substation

$\begin{aligned} \mathbf{B}(a_c, t_0, noisy(substation) \rightarrow unusual) & \mathbf{f_1} \\ \mathbf{P}(a_c, t_1, noisy(substation)) & \mathbf{f_2} \end{aligned}$

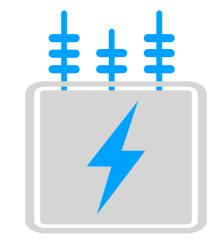


$\forall t : \mathbf{O} \begin{pmatrix} a_c, t, unusual, \\ happens(action(a_c, consult(a_t)), t+1) \end{pmatrix}$ **f**₃

 $\forall t : \mathbf{B}(a_c, t, \mathbf{f}_3) \mathbf{f}_4$



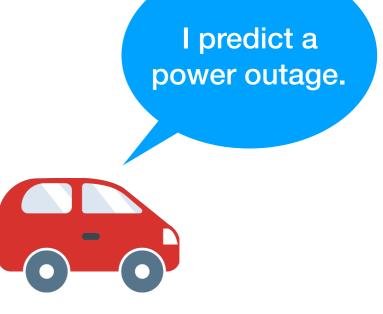
$$\forall a : \begin{pmatrix} happens(action(a, consult(a_t)), t_2) \\ \rightarrow \mathbf{B}(a, t_3, outage) \end{pmatrix} f_5$$



$$\forall t : \mathbf{O} \begin{pmatrix} a_c, t, outage, \\ \mathbf{S}(a_c, a_h, outage, t+1) \end{pmatrix} \mathbf{f}_6$$

$$\forall t : \mathbf{B}(a_c, t, \mathbf{f}_6) \mathbf{f}_7$$









$$\forall t : \mathbf{O}\begin{pmatrix} a_h, t, outage, \\ \forall s : quantity(s) > 0 \end{pmatrix}$$

- Ask smart refrigerator which supplies are necessary
- Place an order online
 - If possible, request same-day drone delivery
 - If not, find a store along human's route home, request store pickup
 - Tell car to reroute human to store before returning home

Scenario II: Office Optimization

- I. Scenario
 - I. A new employee (eric) has been in office for orientation for 3 days
 - 2. Today, the boss (bill) has to assign eric a permanent desk
 - 3. bill employs TAI to help him determine the best desk for eric.
- 2. Therefore, TAI's goal is

$$\exists d : \begin{bmatrix} \mathbf{I} (bill, t^*, happens(action(eric, assigned(d)), t^* + 1)) \\ \land \forall e \begin{bmatrix} (happens(action(eric, assigned(d)), t^* + 1) \land pos_emotion(e, t^* + 1)) \\ \rightarrow pos_emotion(e, t^* + 2) \\ \land \text{ HighlyProductive(eric)} \end{bmatrix}$$

- 3. TAI determines, in a *tentacular* fashion, that desk 3 would be best for *eric*
 - I. The building's smart thermostat was set to a temperature that most employees found comfortable. However, *eric*'s smart watch indicated to TAI that *eric* was cold. Desk 3 is close to the heater.
 - 2. The company's orientation software found that *eric* was most productive when at a desk away from loud-speaking employees. Desk 3 is in a quiet area (as determined by microphones in those areas).

A Comment on Ethics & Privacy

- Clearly could enable nefarious parties to
 - (Potentially unwittingly) influence humans
 - violate the privacy of humans, both consenting users and not
- Ethical/moral reasoning are at the forefront of DCEC/TAI
 - Include statements in TAI's contract to guarantee privacy of users' data
 - Utilize cutting-edge cryptographic methods for hiding sensitive data from TAI
 - homomorphic encryption
 - zero-knowledge proofs
 - differential privacy

Future Work

- Micro-domains and synthetic data in home automation, smart buildings and cities
- Integration of one more more common services with our reasoning systems and planners with a focus on:
 - Safety, Ethics, Efficiency
- Visual Question Answering (VQA) with Justifications
 - Human-understandable justifications from visual scenes

Thank You

Links

- TAI Project: <u>http://kryten.mm.rpi.edu/TAI/tai.html</u>
- Reasoner: <u>https://github.com/naveensundarg/prover</u>